

# Clarity through Competence: Supporting Physics Majors with Specifications Grading

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# Introductory Physics for majors in physics and astronomy

(with calculus)

The mission purpose given to me by the Dept. Chair:

Improve the retention of students in our programs

Improve their academic preparation for upper-level physics courses

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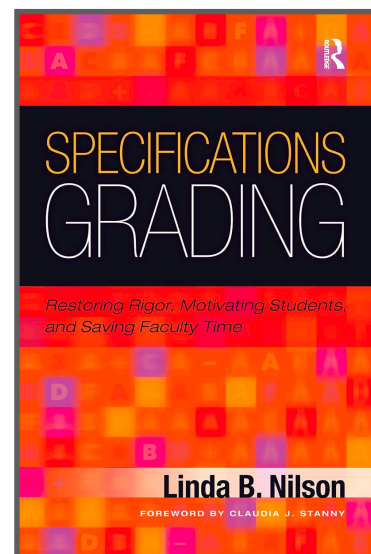
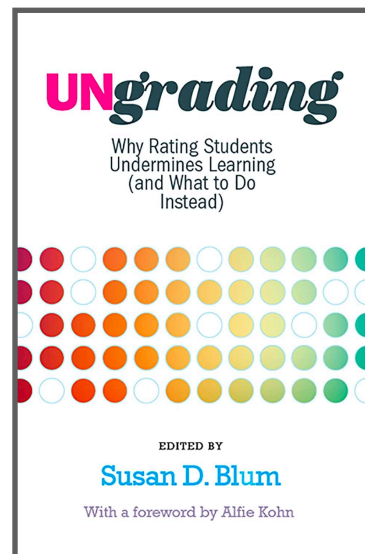
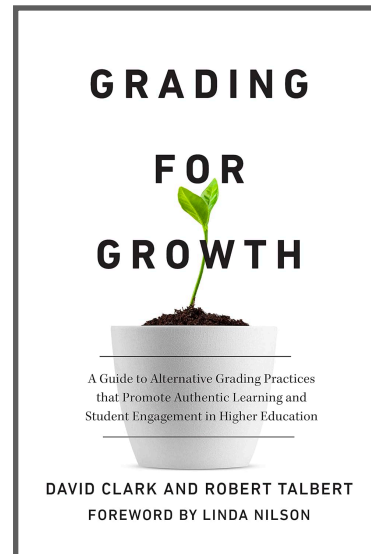
Learn the physics

Develop the skills for  
'Professional Physics Work'

How can we assess *both* of these things?

How can we communicate *clearly* these goals to students?

Just for context



<b>A</b>	◆ Complete <b>All</b> (14) Core Learning Targets and ◆ Complete at least <b>5</b> Extra Learning Targets
<b>B</b>	◆ Complete <b>All</b> (14) Core Learning Targets and ◆ Complete at least <b>2</b> Extra Learning Targets
<b>C</b>	◆ Complete at least <b>12</b> Core Learning Targets
<b>D</b>	◆ Complete at least <b>9</b> Core Learning Targets  (Because of the pre-requisites on LTs, this mean completing Core 1-9)
<b>If you do not meet <i>all</i> of the criteria for any other grade, you will earn an F</b>	

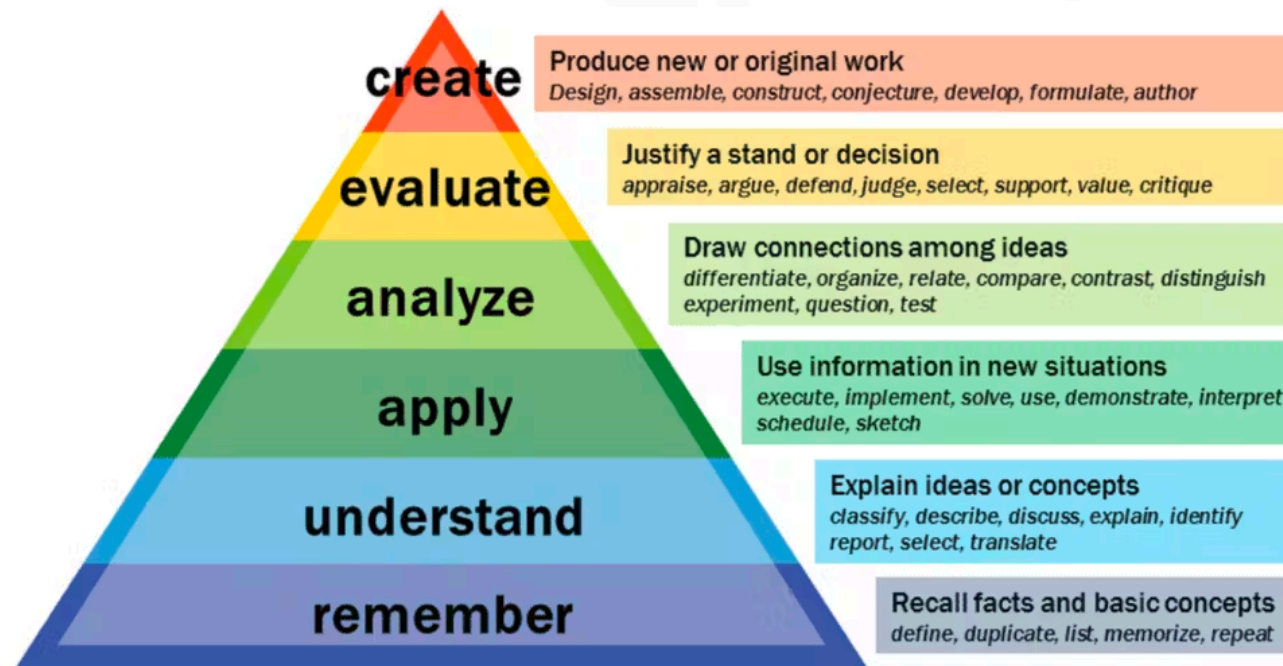
# GRADING FOR GROWTH

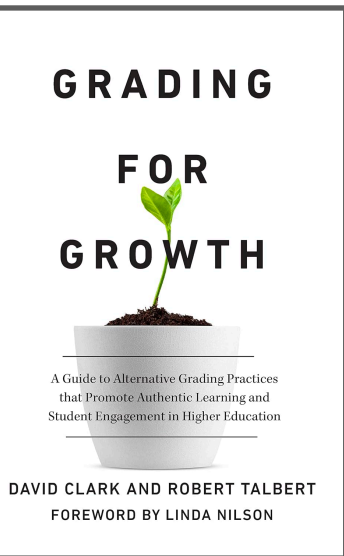
A Guide to Alternative Grading Practices  
that Promote Authentic Learning and  
Student Engagement in Higher Education

DAVID CLARK AND ROBERT TALBERT  
FOREWORD BY LINDA NILSON

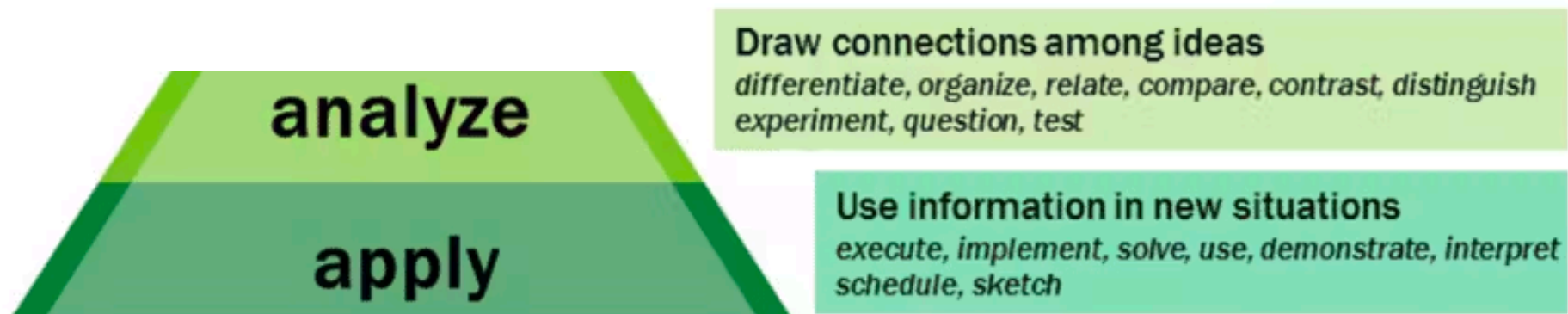


## Bloom's Taxonomy





## **Bloom's Taxonomy**



# Core Learning Targets

## Block #1

1. I can **assess** whether an object has interacted.
2. I can **find** the future position of an object based on its average velocity or its momentum (relativistic or not).
3. I can use logical, non-quantitative but mathematical reasoning to **deduce** the direction of  $\vec{p}_{\text{future}}$ ,  $\vec{F}_{\text{net}}$  or  $\vec{p}_{\text{now}}$ , given the other two.

## Block #2 (pre-requisite Block #1)

4. I can **estimate** the impact force in a sudden collision problem using order of magnitude estimation.
5. I can **predict** motion using the iterative method with a variable force (springs).
6. I can **solve** a kinematic problem with multiple unknowns.
7. I can **solve** a collision problem with conservation of momentum.

## Block #3 (pre-requisite Block #2)

8. I can **find** the stiffness of an interatomic bond based on experimental data.
9. I can **solve** a “detective” problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero.

## Block #4 (pre-requisite Block #3)

10. I can **solve** a problem using the energy principle, when the forces are constants with a point particle system.
11. I can **solve** a problem using the energy principle with a multi-object system and the concept of potential energy.
12. I can **solve** a rolling problem with the energy principle.
13. I can **calculate** the angular momentum of a system and the torque applied by a force to a system.
14. I can **solve** a statics problem with multiple unknowns using the momentum and angular momentum.

# Extra Learning Targets

## Extra Learning Targets (pre-requisite Core Block #3)

1. I can use the properties of a harmonic oscillator to analytically **predict** something about a mass-spring system.
2. I can **solve** a “detective” problem with multiple unknowns, that requires considering more than one system, when the change in momentum is not zero but unidirectional.
3. I can **solve** a “detective” problem with multiple unknowns, that requires one system, when the change in momentum is not zero and non-linear.
4. I can **calculate** the work done by a variable force with integration.
5. I can **relate** the graph of energies versus separation to determine the potential fate of the object.
6. I can **solve** a rotational collision problem.

**Interactions**

Core 1

**Momentum Principle**

Core 2

Core 3

Applications:

Point Object system

Sudden collision

Core 4

Iterative method

Core 5

Special analytical case: constant force

Kinematic problem

Core 6

Multi-Object system

Collision problems

Core 7

Extended objects

Stiffness of interatomic bonds

Core 8

Special analytical case: recall force (harmonic motion)

Harmonic motion

Extra1

Force "detectives"

When there is no change in momentum

Core 9

When there is a change in momentum

Multi-system, unidirectional

Extra2

One-system, Non-linear

Extra3

**Energy Principle**

Point Object system

**Problems with constant forces**

Core10

**Work done by a variable force by integration**

Extra4

Multi-Object system

**Problems using potential energies**

Core11

**Potential fate of objects interacting with a planet**

Extra5

Extended objects

**Rolling problems**

Core12

**Angular momentum Principle**

Core13

Extended objects

No change in angular momentum

**Statics problems**

Core14

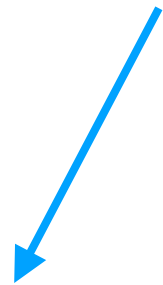
No external torque

**Rotational collisions**

Extra6

*First person*

*An action*



**Learning Target 9:** I can **solve** a “force detective” problem with multiple unknowns, that requires considering more than one system, when the **change in momentum is zero**



*Under which circumstances*

*Under which circumstances*

**Learning Target 10:** I can **solve** a problem using the energy principle, when the forces are constants with a point particle system.

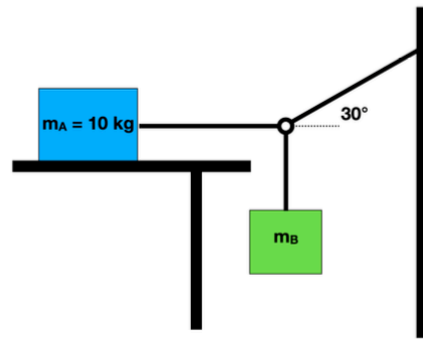
**Learning Target Core 9:** I can **solve** a "detective" problem with multiple unknowns, that requires considering more than one system, when the **change in momentum is zero**

**Why this works:** It's a high-level task with clear constraints. It's not a "plug and chug" problem; it requires structural thinking.

# Learning Target Core 9: I can solve a "detective" problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero

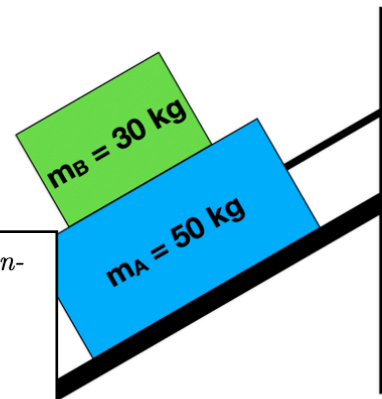
**Learning Target Core 6** I can solve a "detective" problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero

A block rest on a table. The coefficient of static friction between the table and the block is 0.25. The block is connected by a rope to a ring of negligible mass, which is itself connected to a rope attached to a wall (making a  $30^\circ$  angle with the horizontal) and to a vertical rope from which another box is hanging. What is the maximum mass for the hanging box, so that the box on the table does not move? (Hint, I systems: the box on the table, the hanging box, and the ring holding the ropes.)



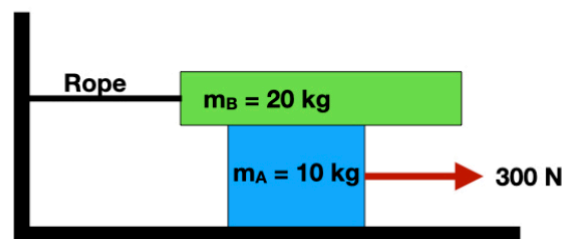
**Learning Target Core 6** I can solve a "detective" problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero

Box A is sitting still on a ramp, which is inclined at  $30^\circ$  with respect to the horizontal. There is no friction between the ramp and Box A. Box A is attached to a wall by a rope of negligible mass. Block B sits on top of Block A and does not slide. Find the minimum coefficient of static friction between the two blocks, and the tension in the rope. Tilt your coordinate system so that the  $x$ -axis points up the ramp.



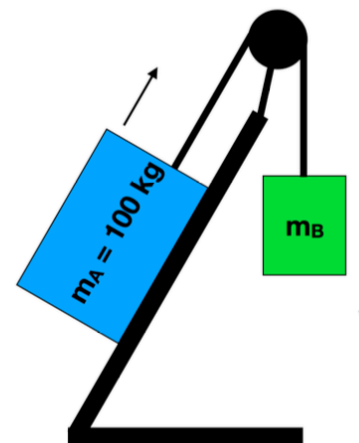
**Learning Target Core 6** I can solve a "detective" problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero

On a table, a block of mass  $m_B = 20$  kg is placed on top of another block of mass  $m_A = 10$  kg. The top block is attached to the wall on the left by a rope. The mass of the rope is very small, and the rope is horizontal. There is friction between the bottom block and the table, as well as between the two blocks. The coefficients of friction are the same between all surfaces. You pull on the bottom block with a force of 300 N. The block moves to the right with a constant velocity. Solve for the tension in the rope.



**Learning Target Core 6** I can solve a "detective" problem with multiple unknowns, that requires considering more than one system, when the change in momentum is zero

Box A (100 kg) is placed on a ramp, which is inclined at  $60^\circ$  with respect to the horizontal. The coefficient of kinetic friction between the ramp and Box A is 0.6 and the coefficient of static friction is 0.7. Box A is attached by rope of negligible mass to Block B. The rope passes over a pulley (the black circle on the diagram) and Block B is hanging on the other side of the ramp. If Block B is **moving downward at constant speed**, what is the mass of Block B?



**Learning Target Core 9:** I can **solve** a "detective" problem with multiple unknowns, that requires considering more than one system, when the **change in momentum is zero**

**Transparency:** Including the rubric with the assignment, not just after it's graded.

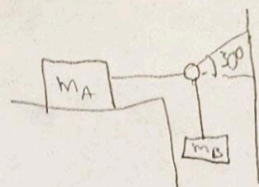
**The Language of Growth:** Moving the conversation from "How many points do I need?" to "What do I need to demonstrate?"

**Raise the bar:** the rubric can include more than "getting an answer"

Physics	
	11. I defined the systems.
	12. I correctly listed all of the interactions and drew them on a free-body diagram.
	13. I wrote a vector expression for each force.
	14. I correctly determined the change in momentum.
	15. I correctly identified and clearly marked reciprocal forces, as needed.
	16. I correctly identified and clearly marked equal tension interactions for mass-less ropes, as needed.
	17. I proved that the problem can be solved and provided a plan for "doing the math".
	18. I mathematically solved for the unknown quantity the problem was asking for, unless the question said not to do so.

# What I am expecting Professional Physics Work to 'look like' ?

$k_s = 0.25$   
 $m_A = 10 \text{ kg}$



①

## Core 6

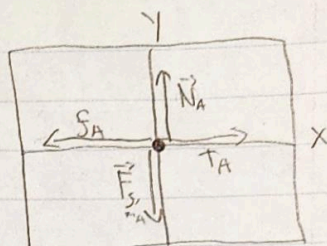
### System 1: Box A

#### Forces at a Distance

Object	magnitude	direction
Earth (gravity)	$m_A g$	$\langle 0, -1, 0 \rangle$ ✓

#### Contact Forces

object	magnitude	direction
Table (normal)	$N_A$	$\langle 0, +1, 0 \rangle$ ✓
Table (friction)	$\mu_s N_A$	$\langle -1, 0, 0 \rangle$ ✓
Rope A (tension)	$T_A$	$\langle +1, 0, 0 \rangle$ ✓



### Momentum Principle

	$d\vec{p}/dt$	$=$	$\vec{F}_{net}$	
x	0	$=$	$T_A - \mu_s N_A$	① ✓
y	0	$=$	$N_A - m_A g$	② ✓
z	0	$=$	0	

Other Systems  
On Next Pages →

### Work

- Because the ropes being used are of a negligible mass, the tensions are the same on both ends of the rope.
- To solve for the maximum mass of the hanging box ( $m_B$ ), we will set the static friction of the table on box A to its max value. ✓
- The problem can be solved because there are 5 equations and unknowns

### Plan

- 1) Use eq ② to solve for  $N_A$
- 2) Use eq ① to solve for  $T_A$
- 3) Use eq ④ to solve for  $T_C$
- 4) Use eq ⑤ to solve for  $T_B$
- 5) Use eq ③ to solve for  $m_B$

Cont →

②

## Core 6 - Cont.

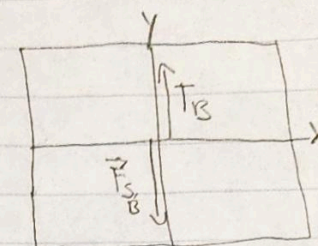
### System 2: Box B

#### Forces at a distance

object	magnitude	direction
Earth (gravity)	$m_B g$	$\langle 0, -1, 0 \rangle$ ✓

#### Contact Forces

object	magnitude	direction
Rope B (tension)	$T_B$	$\langle 0, +1, 0 \rangle$ ✓



### Momentum principle

	$d\vec{p}/dt$	$=$	$\vec{F}_{net}$	
x	0	$=$	0	
y	0	$=$	$T_B - m_B g$	③ ✓
z	0	$=$	0	

### Work Cont

1)  $N_A = m_A g$   
 $= 10 \text{ kg} \cdot 9.8 \frac{\text{m}}{\text{s}^2}$   
 $= 98 \text{ N}$  ✓

4)  $T_B = T_C \sin 30^\circ$   
 $= 28.2 \text{ N} \cdot \sin 30^\circ$   
 $= 14.1 \text{ N}$  ✓

2)  $T_A = \mu_s N_A$   
 $= 0.25 \cdot 98 \text{ N}$   
 $= 24.5 \text{ N}$  ✓

5)  $m_B g = T_B$   
 $m_B = \frac{T_B}{g}$   
 $= \frac{14.1 \text{ N}}{9.8 \frac{\text{m}}{\text{s}^2}}$   
 $= 1.44 \text{ kg}$  ✓

3)  $T_C \cos 30 = T_A$   
 $T_C = \frac{T_A}{\cos 30} = \frac{24.5 \text{ N}}{0.87}$   
 $= 28.2 \text{ N}$  ✓

$\boxed{= 1.44 \text{ kg}}$



# *What I am expecting Professional Physics Work to 'look like' ?*

## **How can we express this?**

**Writing like a Physicist:** Treating the solution as a technical document, not just a scratchpad.

**Satisfactory does not mean perfect:** They are not experts just yet! We need to distinguish between a student being "messy" and a student being "wrong."

For each of your learning standards / grading rubric:  
What is essential, and what is just busy-work?

# Learning Target Core 9: I can **solve** a "detective" problem with multiple unknowns, that requires considering more than one system, when the **change in momentum is zero**

## Rubric

General	
	1. I created a symbol for all the known and unknown quantities relevant to the problem.
	2. I clearly identified which quantity I am looking for.
	3. I wrote the solution in logical sections so that the logical progression is easy to follow.
	4. I included units each time I wrote down a numerical value.
	5. I included $\rightarrow$ for every vector symbols.
	6. I used proper vector notation when writing a vector in components.
	7. I included a sketch of the situation with a coordinate system.
	8. I used clear and concise language to explain the steps of my analysis.
Math	
	9. I used correct vectorial and algebra manipulations.
	10. I used correct unit algebra.
Physics	
	11. I defined the systems.
	12. I correctly listed all of the interactions and drew them on a free-body diagram.
	13. I wrote a vector expression for each force.
	14. I correctly determined the change in momentum.
	15. I correctly identified and clearly marked reciprocal forces, as needed.
	16. I correctly identified and clearly marked equal tension interactions for mass-less ropes, as needed.
	17. I proved that the problem can be solved and provided a plan for "doing the math".
	18. I mathematically solved for the unknown quantity the problem was asking for, unless the question said not to do so.

## Helping students get there: provide clarity

Item	Professional (Pass)	Unsatisfactory (Revise)
<b>Vector Notation</b>	All vector quantities are denoted with an arrow, and are never equated to scalars.	Treating vectors as scalars. Incorrect notation makes an equation invalid. The lack of vector notation makes it ambiguous whether a quantity is a scalar, a magnitude, or a component
<b>Logic Flow</b>	Clear "Story", logic is self-evident to a peer	Random equations in a "cloud."
<b>Grammar</b>	Spelling or grammar errors allowed as long as the textual meaning of the sentence is still accurate.	The written text is illegible or nonsensical.

*In conclusion, my challenge to you*

**Pick one homework/exam question.**

**Verbalize the standard/goal this question is addressing with an action verb and a set of constraints.**

**Think about what are the essential components of satisfactory work that student can use to demonstrate competence.**

**Think also about what are not an essential components of satisfactory work at this moment, and think of examples to give students!**

## Useful resources:

- Grading for Growth blog: <https://gradingforgrowth.com/>
- [alternativegrading.slack.com](https://alternativegrading.slack.com) (there is a Physics channel)
- Blog of Robert Talbert <https://rtalbert.org/> (Mathematics Dept. at Grand Valley State University)

Who I would like to thank for making whole courses available on <https://github.com/RobertTalbert>

